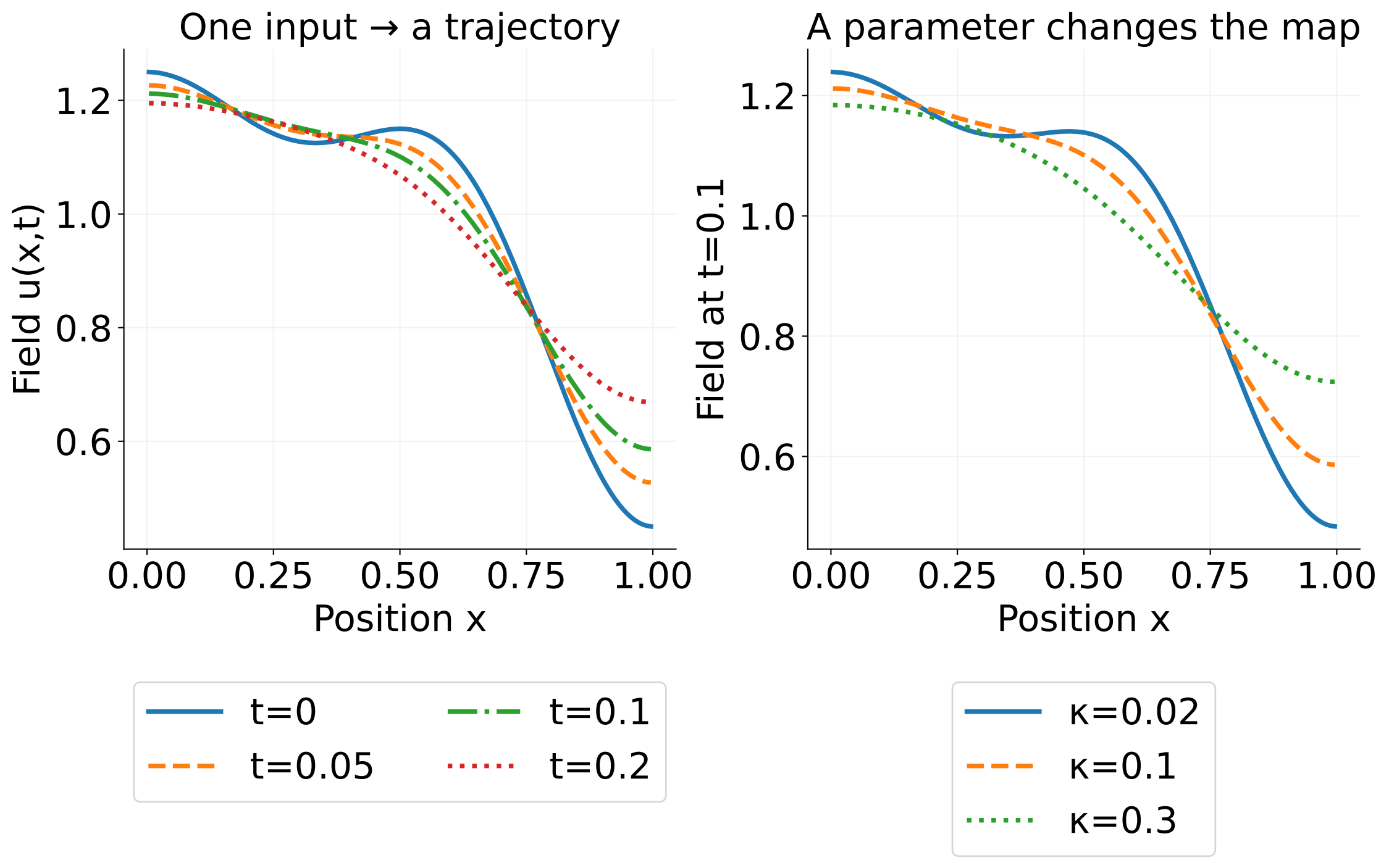

One input → a trajectory
Field u(x,t)
1.2
1.0
0.8
0.6
0.00
0.25
0.50
0.75
1.00
Position x
t=0
t=0.05
t=0.1
t=0.2
A parameter changes the map
Field at t=0.1
1.2
1.0
0.8
0.6
0.00
0.25
0.50
0.75
1.00
Position x
κ=0.02
κ=0.1
κ=0.3